

FORM PTO-1449
(Rev. 7-80)U.S. DEPARTMENT OF COMMERCE
PATENT AND TRADEMARK OFFICEAtty. Docket No.
14395Serial No.
10/615,595

LIST OF PRIOR ART CITED BY APPLICANT

(Use several sheets if necessary)

APPLICANT
KHAJEPOUR et al.FILING DATE
July 9, 2003GROUP
3652

MAR 10 2004

U.S. PATENT DOCUMENTS

EXAMINER INITIAL		DOCUMENT NUMBER							DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
Wells	AA	3	2	8	6	8	5	1	11-22-1966	Sperg			
	AB	3	4	9	7	0	8	3	02-24-1970	Anderson			
	AC	3	6	3	1	7	3	7	01-04-1970	Wells			
	AD	4	6	6	6	3	6	2	05-19-1987	Landsberger et al.			
	AE	4	6	8	3	7	7	3	08-04-1987	Diamond			
	AF	4	9	7	6	5	8	2	12-11-1990	Clavel			
	AG	5	3	1	3	8	5	4	05-25-1994	Akeel			
	AH	5	3	3	3	5	1	4	08-02-1994	Toyama et al.			
Wells	AI	5	9	6	7	7	2	9	10-19-1999	Foes			

OTHER PRIOR ART (Including Author, Title, Date, Pertinent Pages, Etc.)

Wells	BA	"Delta, a Fast Robot with Parallel Geometry", R. Clavel, Proc. Int. Symposium on Industrial robots, April 1988, pp. 91-100.
	BB	"Kinematics of a Three-DOF Platform with Three Extensible Limbs", Lung-Wen Tsai, Recent Advances in Robot Kinematics, pp. 401-409.
	BC	"A Smart Kinesthetic Interactive Platform", M. Griffis et al., Advances in Robot Kinematics and Computationed Geometry, pp. 459-464.
Wells	BD	"Development of an Ultrahigh speed Robot FALCON using Wire Drive System", S. Kawamura et al., IEEE International Conference on Robotics and Automation 1995, pp. 215-220.

EXAMINER Underwood

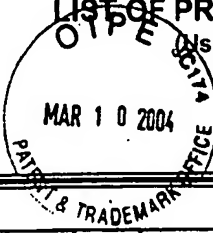
DATE CONSIDERED 12/06/05

EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 602; Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

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EXAMINE R INITIAL		DOCUMENT NUMBER							DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
	AA	4	6	6	6	3	6	2	May 19, 1987	Sheridan et al.			
	AB	5	3	1	3	8	5	4	May 25, 1994	Akeel			
	AC	4	9	7	6	5	8	2	December 11, 1990	Clavel			
	AD												
	AE												
	AF												

FOREIGN PATENT DOCUMENTS

		DOCUMENT NUMBER							DATE	COUNTRY	CLASS	SUBCLASS	TRANSLATION	
													YES	NO
	BA	11	0	7	7	5	7	7	06/30/1999	JP				

OTHER PRIOR ART (Including Author, Title, Date, Pertinent Pages, Etc.)

	ca		Maeda, K. et al., "On Design of a redundant Wire-Driven Parallel robot WARP Manipulator", Proceedings of the 1999 IEEE International Conference on Robotics & Automation, May 1999, pp. 895-900.										
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